

# Gaussian Process Regression

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# Gaussian Process Regression

## Introduction

- Gaussian Process (GP) is a *non-parametric probabilistic* approach.
- GP extends the concept of Gaussian distribution of numbers to *functions!*
- A GP is defined by a mean function (often zero) and a *covariance function* or *kernel*:

$$k(x, x') = \sigma_f^2 \exp \left[ \frac{-(x - x')^2}{2l^2} \right]$$

Optimizable parameters

- $y = f(x)$  and  $y_*$  (prediction for new  $x_*$ ) make a *joint* Gaussian distribution:

$$\begin{matrix} \text{cal} \\ \text{val} \end{matrix} \begin{matrix} \boxed{\mathbf{y}} \\ \boxed{y_*} \end{matrix} \sim \mathcal{N} \left( \mathbf{0}, \begin{bmatrix} K & K_*^T \\ K_* & K_{**} \end{bmatrix} \right)$$

Covariance matrices

- *Conditional* probability  $p(y_* | \mathbf{y})$ :

$$y_* | \mathbf{y} \sim \mathcal{N} \left( K_* K^{-1} \mathbf{y}, K_{**} - K_* K^{-1} K_*^T \right)$$

Best estimate:  $\bar{y}_*$

Uncertainty:  $s^2$

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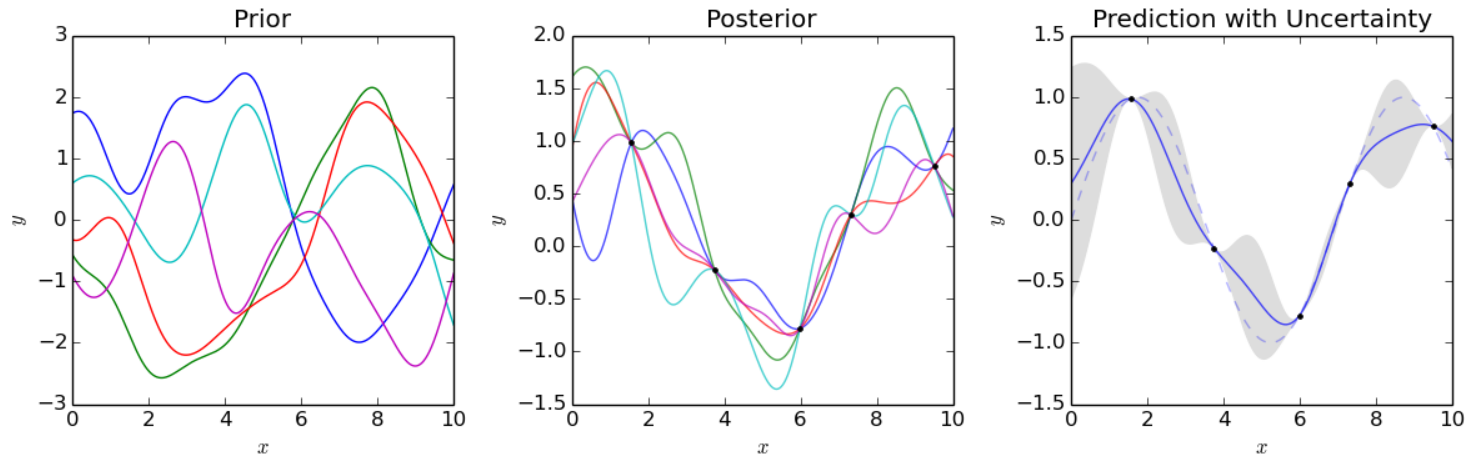
Best estimate:  $\bar{y}_*$

Uncertainty:  $\sigma^2$

# Gaussian Process Regression

## Introduction

GP begins with a **prior** distribution and updates this prior as **new data** are observed, producing the **posterior** distribution over functions.



Great demo: <http://www.tmpl.fi/gp/>

# Gaussian Process Regression

## Benefits

- Non-linear
- Kernel parameters automatically learned from data
- Different kernels can be combined together
- Automatic feature selection (ARD)
- Fully probabilistic predictions
- Fairly resistant to over-fitting

# GPR on the Challenge data

## Settings

- 207 redundant samples removed from calibration set
- Pre-processing: ***SG(1,15,2) + SNV***
- Kernel: ***Matérn  $\nu=5/2$***
- Kernel Parameters optimized by maximizing marginal likelihood
- Inference method: ***Gaussian likelihood***

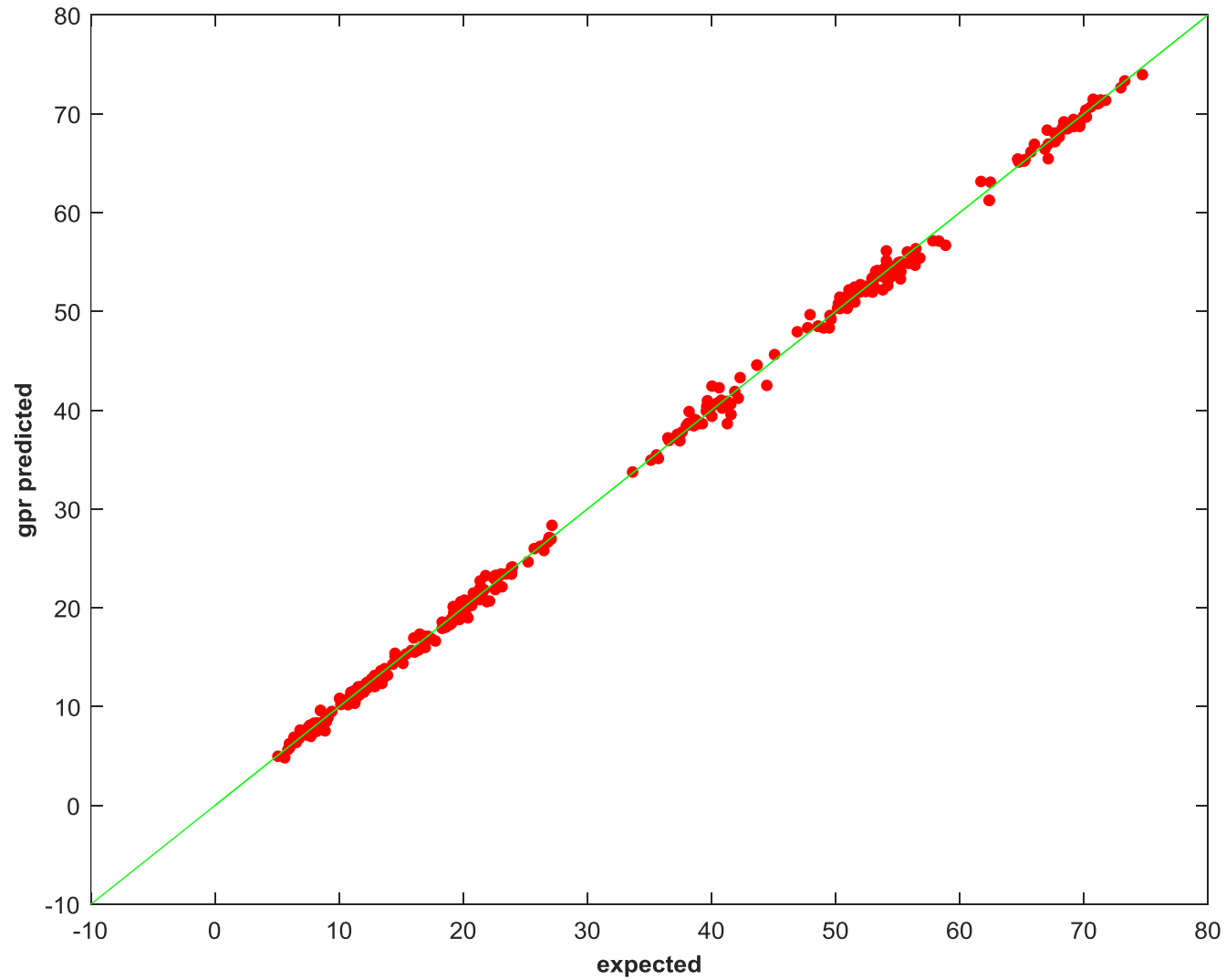
**GPML** Matlab Code version 4.1

(by Carl Edward Rasmussen and Hannes Nickisch)

<http://www.gaussianprocess.org/gpml/>

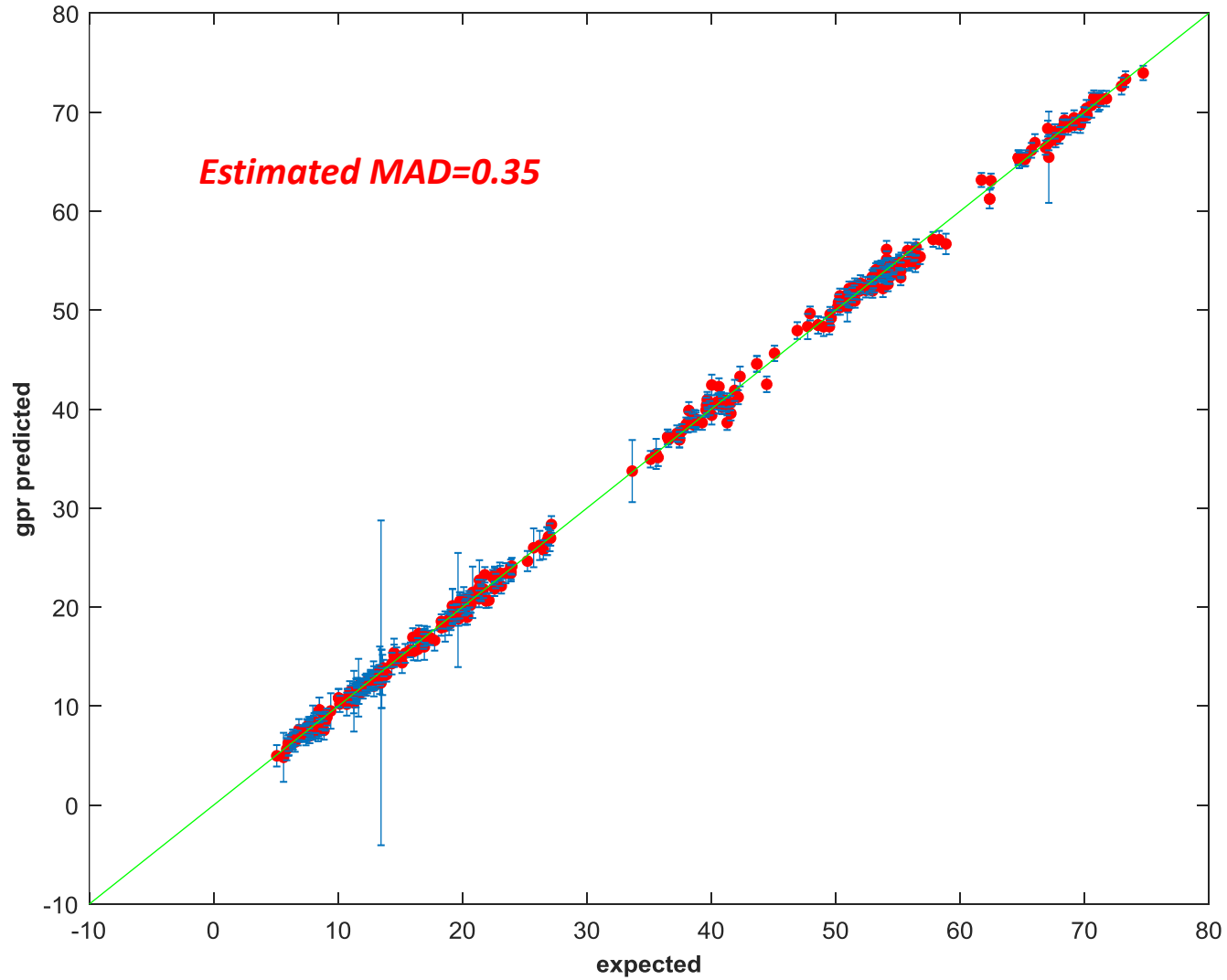
# GPR on the Challenge data

Internal validation



# GPR on the Challenge data

## Internal validation

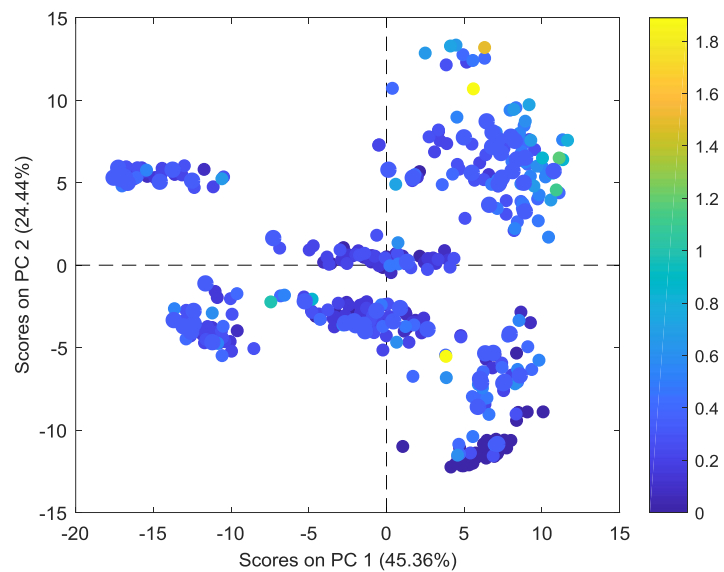




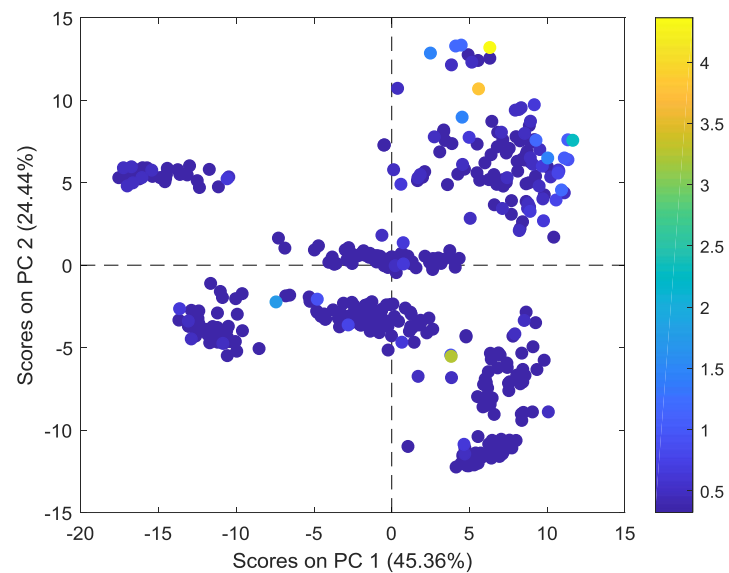
# GPR on the Challenge data

Validation set

## Nearest neighbour distance



## GPR estimated standard deviation





*Merci*